

# Fast-slow systems with chaotic noise

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## Fast-slow systems

We consider **fast-slow** systems of the form

$$\begin{aligned}\frac{dX}{dt} &= \varepsilon h(X, Y) + \varepsilon^2 f(X, Y) \\ \frac{dY}{dt} &= g(Y),\end{aligned}$$

where  $\varepsilon \ll 1$ .

$\frac{dY}{dt} = g(Y)$  be some **mildly chaotic** ODE with state space  $\Lambda$  and ergodic invariant measure  $\mu$ . (**eg.** 3d Lorenz equations.)

$h, f : \mathbb{R}^n \times \Lambda \rightarrow \mathbb{R}^n$  and  $\int h(x, y) \mu(dy) = 0$ .

Our aim is to find a **reduced equation** for  $X$ .

## Fast-slow systems

If we rescale to **large time scales** ( $\sim \varepsilon^{-2}$ ) we have

$$\begin{aligned}\frac{dX_\varepsilon}{dt} &= \varepsilon^{-1}h(X_\varepsilon, Y_\varepsilon) + f(X_\varepsilon, Y_\varepsilon) \\ \frac{dY_\varepsilon}{dt} &= \varepsilon^{-2}g(Y_\varepsilon),\end{aligned}$$

We turn  $X_\varepsilon$  into a random variable by taking  $Y(0) \sim \mu$ .

The aim is to characterise the **distribution** of the random path  $X_\varepsilon$  as  $\varepsilon \rightarrow 0$ .

## Fast-slow systems as SDEs

Consider the simplified **slow** equation

$$\frac{dX_\varepsilon}{dt} = \varepsilon^{-1} h(X_\varepsilon) v(Y_\varepsilon) + f(X_\varepsilon)$$

where  $h : \mathbb{R}^n \rightarrow \mathbb{R}^{n \times d}$  and  $v : \Lambda \rightarrow \mathbb{R}^d$  with  $\int v(y) \mu(dy) = 0$ .

If we write  $W_\varepsilon(t) = \varepsilon^{-1} \int_0^t v(Y_\varepsilon(s)) ds$  then

$$X_\varepsilon(t) = X_\varepsilon(0) + \int_0^t h(X_\varepsilon(s)) dW_\varepsilon(s) + \int_0^t f(X_\varepsilon(s)) ds$$

where the integral is of Riemann-Stieltjes type ( $dW_\varepsilon = \frac{dW_\varepsilon}{ds} ds$ ).

## Invariance principle for $W_\varepsilon$

We can write  $W_\varepsilon$  as

$$W_\varepsilon(t) = \varepsilon \int_0^{t/\varepsilon^2} v(Y(s)) ds = \varepsilon \sum_{j=0}^{\lfloor t/\varepsilon^2 \rfloor - 1} \int_j^{j+1} v(Y(s)) ds$$

The assumptions on  $Y$  lead to **decay of correlations** for the sequence  $\int_j^{j+1} v(Y(s)) ds$ .

For very general classes of chaotic  $Y$ , it is known that  $W_\varepsilon \Rightarrow W$  in the sup-norm topology, where  $W$  is a multiple of Brownian motion.

We will call this class of  $Y$  **mildly chaotic**.

## What about the SDE?

Since

$$X_\varepsilon(t) = X_\varepsilon(0) + \int_0^t h(X_\varepsilon(s)) dW_\varepsilon(s) + \int_0^t f(X_\varepsilon(s)) ds$$

This suggest a limiting SDE

$$\bar{X}(t) = \bar{X}(0) + \int_0^t h(\bar{X}(s)) \star dW(s) + \int_0^t f(\bar{X}(s)) ds$$

But how should we interpret  $\star dW$  ? Stratonovich? Itô? neither?

For **additive noise**  $h(x) = I$   
the answer is simple.

## Continuity with respect to noise (Sussmann '78)

Consider

$$X(t) = X(0) + \int_0^t dU(s) + \int_0^t f(X(s))ds ,$$

where  $U$  is a uniformly continuous path.

The above equation is well defined and moreover  $\Phi : U \rightarrow X$  is **continuous** in the sup-norm topology.

Also works in the multiplicative noise case ( $h(X)dU$ ) but only when  $U$  is one dimensional.



## The simple case (Melbourne, Stuart '11)

If the flow is mildly chaotic ( $W_\varepsilon \Rightarrow W$ ) then  $X_\varepsilon \Rightarrow \bar{X}$  in the sup-norm topology, where

$$d\bar{X} = dW + f(\bar{X})ds .$$

In the multiplicative  $1d$  noise case, the limit is Stratonovich

$$d\bar{X} = h(\bar{X}) \circ dW + f(\bar{X})ds .$$

# The strategy

The solution map takes “irregular path space” to “solution space”

$$\Phi : W_\varepsilon \mapsto X_\varepsilon$$

If this map were **continuous** then we could lift  $W_\varepsilon \Rightarrow W$  to  $X_\varepsilon \Rightarrow X$ .

When the noise is both  
**multidimensional** and  
**multiplicative**, this strategy fails.

## Ito, Stratonovich and family

SDEs are very **sensitive** wrt approximations of BM.

Suppose

$$dX = h(X)dW + f(X)dt$$

and define an approximation

$$dX_n = h(X_n)dW_n + f(X_n)dt$$

with some approximation  $W_n$  of  $W$ .

Taking  $n \rightarrow \infty$ ,  $X_n$  might converge to something completely different to  $X$ . It all depends on the approximation  $W_n$ .

**Eg. 1** If  $W_n$  is a step function approximation of  $W$ , then  $X_n$  converges to the **Ito** SDE

$$dX = h(X)dW + f(X)dt$$

**Eg. 2** (Wong-Zakai) If  $W_n$  is a linear interpolation of  $W$ , then  $X_n$  converges to the **Stratonovich** SDE

$$dX = h(X) \circ dW + f(X)dt$$

**Eg. 3** (McShane, Sussman) If  $W_n$  is a higher order interpolation of  $W$ , we can get limits which are **neither Ito nor Stratonovich**.

It is not enough to know that

$$W_n \rightarrow BM.$$

We need more information.

## Rough path theory (Lyons '97)

Provides a **unified** definition of a DE driven by a noisy path

$$X(t) = X(0) + \int_0^t h(X(s))dU(s) + \int_0^t h(X(s))ds$$

when the  $dU$  integral is not well defined.

In addition to  $U$  we must be given another path  $\mathbb{U} : [0, T] \rightarrow \mathbb{R}^{d \times d}$  which is (formally) an iterated integral

$$\mathbb{U}^{ij}(t) \stackrel{\text{def}}{=} \int_0^t U^i(s)dU^j(s).$$

These extra components tells us how to interpret the **method of integration**.

## Rough path theory (Lyons '97)

Given a “rough path”  $\mathbf{U} = (U, \mathbb{U})$  we can construct a solution

$$X(t) = X(0) + \int_0^t h(X(s)) d\mathbf{U}(s) + \int_0^t h(X(s)) ds$$

**Eg. 1** If  $U = W$  and  $\mathbb{U} = \int W dW$  is the Ito iterated integral, then the constructed  $X$  is the solution to the Ito SDE.

**Eg. 2** If  $U = W$  and  $\mathbb{U} = \int W \circ dW$  is the Stratonovich iterated integral, then the constructed  $X$  is the solution to the Stratonovich SDE.



## Rough path theory (Lyons '97)

Most importantly (for us) the map

$$\Phi : (U, \mathbb{U}) \mapsto X$$

is an extension of the classical solution map and is **continuous** with respect to the “rough path topology”.

# Convergence of fast-slow systems

Returning to the slow variables

$$X_\varepsilon(t) = X_\varepsilon(0) + \int_0^t h(X_\varepsilon(s)) dW_\varepsilon(s) + \int_0^t f(X_\varepsilon(s)) ds$$

If we let

$$W_\varepsilon^{ij}(t) = \int_0^t W_\varepsilon^i(r) dW_\varepsilon^j(r)$$

then  $X_\varepsilon = \Phi(W_\varepsilon, W_\varepsilon)$ .

Due to the continuity of  $\Phi$ , if  $(W_\varepsilon, W_\varepsilon) \Rightarrow (W, W)$ , then  $X_\varepsilon \Rightarrow \bar{X}$ , where

$$\bar{X}(t) = \bar{X}(0) + \int_0^t h(\bar{X}(s)) dW(s) + \int_0^t f(\bar{X}(s)) ds$$

with  $W = (W, W)$ .

## Theorem (K. & Melbourne '14)

If the *fast* dynamics are mildly chaotic, then  $(W_\varepsilon, \mathbb{W}_\varepsilon) \Rightarrow (W, \mathbb{W})$  where  $W$  is a Brownian motion and

$$\mathbb{W}^{ij}(t) = \int_0^t W^i(s) dW^j(s) + \lambda^{ij} t$$

where the integral is Itô type and

$$\lambda^{ij} = \int_0^\infty \mathbf{E}_\mu \{ v^i(Y(0)) v^j(Y(s)) \} ds .$$

$$\text{Cov}^{ij}(W) = \int_0^\infty \mathbf{E}_\mu \{ v^i(Y(0)) v^j(Y(s)) + v^j(Y(0)) v^i(Y(s)) \} ds$$

# Homogenized equations

## Corollary

Under the same assumptions as above, the *slow* dynamics  $X_\varepsilon \Rightarrow \bar{X}$  where

$$d\bar{X} = h(\bar{X})dW + \left( f(\bar{X}) + \sum_{i,j,k} \lambda^{ij} \partial^k h^i(\bar{X}) h^{kj}(\bar{X}) \right) dt .$$

in Itô form, with  $\lambda^{ij} = \int_0^\infty \mathbf{E}_\mu \{ v^i(Y(0)) v^j(Y(s)) \} ds$

$$d\bar{X} = h(\bar{X}) \circ dW + \left( f(\bar{X}) + \sum_{i,j,k} \lambda^{ij} \partial^k h^i(\bar{X}) h^{kj}(\bar{X}) \right) dt$$

in Stratonovich form, with

$\lambda^{ij} = \int_0^\infty \mathbf{E}_\mu \{ v^i(Y(0)) v^j(Y(s)) - v^j(Y(0)) v^i(Y(s)) \} ds .$

## Proof I : Find a martingale

The strategy is to decompose

$$W_\varepsilon(t) = M_\varepsilon(t) + A_\varepsilon(t)$$

where  $M_\varepsilon$  is a **good** martingale sequence (**Kurtz-Protter** 92)

$$\left( U_\varepsilon, M_\varepsilon, \int U_\varepsilon dM_\varepsilon \right) \Rightarrow \left( U, W, \int U dW \right)$$

where the integrals are of **Itô** type.

And  $A_\varepsilon \rightarrow 0$  uniformly, but oscillates rapidly. Hence  $A_\varepsilon$  is like a **corrector**.

## Proof II : Martingale approximation (Gordin 69)

Introduce a Poincaré section  $\Lambda$  with Poincaré map  $T$  and return times  $\tau_j$ . Write

$$\begin{aligned} W_\varepsilon(t) &= \varepsilon \sum_{j=0}^{N(\varepsilon^{-2}t)-1} \int_{\tau_j}^{\tau_{j+1}} v(Y(s)) ds \\ &= \varepsilon \sum_{j=0}^{N(\varepsilon^{-2}t)-1} \tilde{v}(T^j Y(0)) = \varepsilon \sum_{j=0}^{N(\varepsilon^{-2}t)-1} V_j. \end{aligned}$$

We have a CLT sum for a stationary random sequence  $\{V_j\}$  with natural filtration  $\mathcal{F}_j = T^{-j}\mathcal{M}$  (where  $\mathcal{M}$  is the  $\sigma$ -algebra for the  $Y(0)$  probability space )

## Proof II : Martingale approximation (Gordin 69)

Use a **martingale approximation** to show that  $\varepsilon \sum_j^{N_\varepsilon-1} V_j \Rightarrow W$ .

Write  $V_j = M_j + (Z_j - Z_{j+1})$  where  $\mathbf{E}(M_j | \mathcal{F}_j) = 0$ .

A good choice (if it converges) is the series

$$Z_j = \sum_{k=0}^{\infty} \mathbf{E}(V_{j+k} | \mathcal{F}_j).$$

Convergence of this series is guaranteed by **decay of correlations** for the Poincaré map.

## Proof II : Martingale approximation (Gordin 69)

The **good** martingale is  $M_\varepsilon(t) = \varepsilon \sum_{j=0}^{N_\varepsilon-1} M_j$  and the **corrector** is  $A_\varepsilon(t) = \varepsilon(Z_0 - Z_{N_\varepsilon-1})$ . We then get

$$W_\varepsilon(t) = \varepsilon \sum_{j=0}^{N(\varepsilon^{-2}t)-1} M_j + \varepsilon(Z_0 - Z_{N_\varepsilon-1}) \Rightarrow W(t) + 0$$

by **Martingale CLT** and boundedness of  $Z$ .

*We are sweeping a lot under the rug here since  $\mathcal{F}_j \supseteq \mathcal{F}_{j+1}$ . Need to reverse the martingales.*



## Proof III: Computing the iterated integral

To compute  $\mathbb{W}_\varepsilon$  we decompose it

$$\int W_\varepsilon dW_\varepsilon = \int M_\varepsilon dM_\varepsilon + \int M_\varepsilon dA_\varepsilon + \int A_\varepsilon dM_\varepsilon + \int A_\varepsilon dA_\varepsilon$$

Since  $M_\varepsilon$  is a **good** martingale sequence

$$\int M_\varepsilon dM_\varepsilon \Rightarrow \int W dW \quad \int A_\varepsilon dM_\varepsilon \Rightarrow 0.$$

Even though  $A_\varepsilon = O(\varepsilon)$ , the iterated term  $A_\varepsilon dA_\varepsilon$  does not vanish. The last two terms are computed as ergodic averages

$$\int M_\varepsilon dA_\varepsilon + \int A_\varepsilon dA_\varepsilon \rightarrow \lambda t \quad (a.s)$$

## Extensions + Future directions

- The **general** fast-slow system (with  $h(x, y)$ ) can be treated with **infinite dimensional** rough paths (or alternatively, rough flows - Bailleul+Catellier )
- Rough path tools can be adapted to address **discrete-time** fast-slow maps.
- Fast-slow systems with **feedback**. Ergodic properties of  $Y^X$  are poorly understood.
- Stochastic **PDE** limits; **regularity structures**.

## References

- 1 - D. Kelly & I. Melbourne. *Smooth approximations of SDEs*. To appear in **Ann. Probab.** (2014).
- 2 - D. Kelly & I. Melbourne. *Deterministic homogenization of fast slow systems with chaotic noise*. arXiv (2014).
- 3 - D. Kelly. *Rough path recursions and diffusion approximations*. To appear in **Ann. App. Probab.** (2014).

All my slides are on my website ([www.dtbkelly.com](http://www.dtbkelly.com)) **Thank you!**